

Differential Algebraic Geometry, Part I

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- *Differential algebraic geometry*: A new geometry.
- *Founded on*: Commutative differential algebra (J. F. Ritt, 1930).
- *Differential algebraic varieties*: Solution sets of algebraic differential equations.
- *Model*: Algebraic geometry.
- *Geometric points for Ritt*: n -tuples of functions meromorphic in a region of \mathbb{C}^m .
- *Aim*: Unify and clarify the 19th century theory of algebraic differential equations.
- *Ritt's Focus*: Algorithms, similar to Buchberger's in Gröbner basis theory – designed to decide ideal membership; simplify differentiation-elimination.

- *Differential algebraic group theory*: Group objects in this new geometry.
- *Galois groups in a generalized differential Galois theory*: Fundamental matrices in Picard-Vessiot theory depend on parameters.
- *Central in Buium-Pillay-Hrushovski approach to Diophantine problems over function fields*.
- *Symmetry groups of systems of algebraic differential equations*.

- *Ellis R. Kolchin*: Ritt's geometry with a Weil approach.
- *Kolchin topology*: Adaptation of the Zariski topology.
- *Geometric points*: n -tuples with coordinates in a differential field.
- *Kolchin axiomatic treatment – abstract differential algebraic varieties*
Emphasis –specializations of generic points.
- *Jerry Kovacic's differential schemes*: Framework– Grothendieck theory of schemes.

We begin: The Ritt-Kolchin theory of affine differential algebraic geometry. Time permitting: Kovacic's *differential schemes*.

Commutative differential algebra

All rings contain the field \mathbb{Q} of rational numbers, and are associative, commutative, with unit 1. The 0 ring is the only ring for which $1 = 0$.

Definition

Let Θ be the free commutative monoid on the set $\Delta = \{\delta_1, \dots, \delta_m\}$ of *derivation operators*. The elements of the monoid Θ are called *derivative operators*. The derivative operator

$$\theta = \delta_1^{i_1} \dots \delta_m^{i_m}$$

has *order* $r = i_1 + \dots + i_m$. Denote by $\Theta(r)$ the set of all $\theta \in \Theta$ whose order is $\leq r$.

Definitions

A ring \mathcal{R} is a Δ -ring if there is a map from Δ into the multiplicative monoid $\text{End}(\mathcal{R}, +)$, with the additional conditions that for $\delta, \delta' \in \Delta$,

$$\delta\delta' = \delta'\delta,$$

and

$$\delta(ab) = a\delta b + b\delta a, \quad a, b \in \mathcal{R}, \quad \delta \in \Delta.$$

Definition

Δ -subrings and extension rings are defined in such a way that the actions of Δ are compatible. We refer to a Δ -extension ring of a Δ -ring \mathcal{R} as a Δ -*R-algebra*.

Definition

The set \mathcal{R}^Δ of $c \in \mathcal{R}$ with $\delta c = 0$, $\delta \in \Delta$, is a Δ -subring of \mathcal{R} called the *ring of constants* of Δ . If \mathcal{R} is a Δ -field, \mathcal{R}^Δ is a Δ -subfield.

The action of Δ on a Δ -ring \mathcal{R} extends uniquely to a homomorphism from Θ into the multiplicative monoid $\text{End}(\mathcal{R}, +)$. This homomorphism maps Δ into $\text{Der}(\mathcal{R})$.

- ① $1 \in \mathcal{R}^\Delta$. For, if $\delta \in \Delta$,
 $\delta(1) = \delta(1 \cdot 1) = 1 \cdot \delta(1) + \delta(1) \cdot 1 = \delta(1) + \delta(1)$. Thus,
 $\delta(1) = 0$.
- ② If $a \in \mathcal{R}$ is invertible, then $\forall \delta \in \Delta$

$$0 = \delta(1) = \delta(a \cdot a^{-1}) = a\delta(a^{-1}) + \delta(a)a^{-1}.$$

$$\delta(a^{-1}) = -\frac{\delta(a)}{a^2}.$$

$$\delta\left(\frac{b}{a}\right) = \delta\left(b \cdot \frac{1}{a}\right) = b\delta\left(\frac{1}{a}\right) + \delta(b)\frac{1}{a} = -\frac{b\delta(a)}{a^2} + \frac{\delta(b)}{a}$$

So, we have the quotient rule

$$\delta\left(\frac{b}{a}\right) = \frac{a\delta(b) - b\delta(a)}{a^2}.$$

If a Δ -ring \mathcal{R} is an integral domain, its Δ -ring structure extends uniquely to the quotient field of \mathcal{R} .

Definition

Let $z = (z_1, \dots, z_n)$ be a family of elements of a Δ - \mathcal{R} -algebra. The Δ - \mathcal{R} -algebra

$$\mathcal{R}\langle z \rangle = \mathcal{R}[\Theta z] = \varinjlim_{\text{ord } \theta \leq r} \mathcal{R}[\theta z].$$

It is said to be Δ -finitely generated by z . If z_1, \dots, z_n lie in a Δ -extension field of a Δ -field \mathcal{F} , the Δ - \mathcal{F} -extension

$$\mathcal{F}\langle z \rangle = \mathcal{F}(\Theta z) = \varinjlim_{\text{ord } \theta \leq r} \mathcal{F}(\theta z).$$

It is said to be Δ -finitely generated by z .

Example

Let $\mathcal{F} = \mathbb{C}(x, t)$, $\Delta = \{\partial_x, \partial_t\}$. Let

$$\mathcal{G} = \mathcal{F} \langle x^{t-1} e^{-x} \rangle,$$

where we have chosen a Δ -extension field of meromorphic functions, containing $x^{t-1} e^{-x}$.

$$x^{t-1} e^{-x} = e^{(t-1) \log x - x}$$

$$\partial_x (x^{t-1} e^{-x}) = x^{t-1} e^{-x} \left(\frac{t-1-x}{x} \right).$$

$$\partial_t (x^{t-1} e^{-x}) = x^{t-1} e^{-x} \log x.$$

$$\mathcal{G} = \mathbb{C}(x, t) \langle x^{t-1} e^{-x}, \log x \rangle.$$

Let

$$\mathcal{H} = \mathcal{F} \langle \gamma \rangle, \quad \gamma = \int_0^x s^{t-1} e^{-s} ds,$$

where we have chosen an appropriate Δ -extension field of \mathcal{F} .

$$\partial_x \gamma = x^{t-1} e^{-x}.$$

$$\partial_t \gamma = \int_0^x (\log s) s^{t-1} e^{-s} ds.$$

$$\mathcal{H} = \mathbb{C}(x, t) (x^{t-1} e^{-x}, \log x) (\gamma, \partial_t \gamma, \partial_t^2 \gamma, \dots).$$

The "special function" $\gamma = \gamma(x, t)$ is called the (*lower*) *incomplete gamma function*, and is prominent in statistics and physics. The family $(\gamma, \partial_t \gamma, \partial_t^2 \gamma, \dots)$ is algebraically independent over \mathcal{G} (Hölder 1887 (complete gamma), Johnson, Rubel, Reinhart 1995 incomplete gamma).

Theorem

Let \mathcal{R} be a Δ -ring. Let

$$(y_{i\theta})_{1 \leq i \leq n, \theta \in \Theta}.$$

be a family of indeterminates over \mathcal{R} . There is a unique structure of Δ -ring on the polynomial ring $\mathcal{S} = \mathcal{R}[(y_{i\theta})_{1 \leq i \leq n, \theta \in \Theta}]$ extending the Δ -ring structure on \mathcal{R} and satisfying the condition that for every $\delta \in \Delta$, and pair (i, θ)

$$\delta y_{i\theta} = y_{i, \delta\theta}.$$

Note: By definition, $y_{i, \theta\theta'} = y_{i, \theta'\theta}$.

Example

$\mathcal{R} = \mathbb{Z}[x, t]$, $\Delta = \{\partial_x \partial_t\}$, $n = 1$. $\mathcal{S} = \mathbb{Z}[x, t][y, y_x, y_t, y_{xx}, y_{xt}, y_{tt}, \dots]$.
 $P = xy^3 + xt^2yy_x^3y_t^{29}$. Set $\delta = \partial_x$. Extend δ to \mathcal{S} .

Want:

$$\partial_x y = y_x,$$

$$\partial_x y_x = y_{xx},$$

$$\partial_x y_t = y_{xt}.$$

The proof will be broken up into lemmas.

Lemma

There is a unique derivation ∇ on \mathcal{S} such that $\nabla|_R = \delta$, and

$$\nabla y_{i\theta} = 0$$

for every pair (i, θ) .

Proof.

Let $\delta \in \Delta$. For $P \in \mathcal{S}$, let P^δ be the polynomial obtained by differentiating the coefficients of P .

Let \mathfrak{M} be the monomial basis of \mathcal{S} . Let

$$P = \sum_{M \in \mathfrak{M}} a_M M, \quad a_M \in \mathcal{R}, \quad \forall M \in \mathfrak{M}, \quad a_M = 0, \quad a \forall M.$$

$$\nabla P = P^\delta = \sum_{M \in \mathfrak{M}} (\delta a_M) M.$$

∇ is a derivation on \mathcal{S} with the desired properties. □

Example

$$\mathcal{R} = \mathbb{Z}[x, t], \Delta = \{\partial_x \partial_t\}, n = 1. \quad \mathcal{S} = \mathbb{Z}[x, t][y, y_x, y_t, y_{xx}, y_{xt}, y_{tt}, \dots].$$
$$P = xy^3 + xt^2yy_x^3y_t^{29}. \quad \text{Set } \delta = \partial_x$$
$$\nabla P = y^3 + t^2yy_x^3y_t^{29}.$$

Lemma

There is a unique derivation D on \mathcal{S} such that $D|_{\mathcal{R}} = 0$ and

$$Dy_{i\theta} = y_{i,\delta\theta}.$$

Proof.

Define

$$DP = \sum_{1 \leq i \leq n, \theta \in \Theta} \frac{\partial P}{\partial y_{i\theta}} y_{i,\delta\theta}$$
$$Dy_{i\theta} = y_{i,\delta\theta}.$$

D is a derivation on \mathcal{S} with the desired properties. □

Example

$\mathcal{R} = \mathbb{Z}[x, t], \Delta = \{\partial_x \partial_t\}, n = 1. \mathcal{S} = \mathbb{Z}[x, t][y, y_x, y_t, y_{xx}, y_{xt}, y_{tt}, \dots].$
 $P = xy^3 + xt^2yy_x^3y_t^{29}.$ Set $\delta = \partial_x$

$$\begin{aligned} DP &= \frac{\partial P}{\partial y} y_x + \frac{\partial P}{\partial y_x} y_{xx} + \frac{\partial P}{\partial y_t} y_{xt} \\ &= 3xy^2 y_x + xt^2 y_x^3 y_t^{29} + 3xt^2 y y_x^2 y_t^{29} + 29xt^2 y y_x^3 y_t^{28}. \end{aligned}$$

Lemma

For $\delta \in \Delta$, define the extension of δ to $\mathcal{S} = \mathcal{R} [(y_{i\theta})_{1 \leq i \leq n, \theta \in \Theta}]$ to be the derivation

$$\delta = \nabla + D.$$

This definition extends the action of Δ from the coefficient ring to the polynomial algebra.

Proof.

By abuse of language, write

$$D = \sum_{1 \leq i \leq n, \theta \in \Theta} \frac{\partial}{\partial y_{i\theta}} y_{i,\delta\theta},$$

If

$$P = \sum_{M \in \mathfrak{M}} a_M M.$$

$$\delta P = \sum_{M \in \mathfrak{M}} (\delta a_M) M + \sum_{i,\theta} \frac{\partial P}{\partial y_{i\theta}} y_{i,\delta\theta}.$$

Let $\delta' = \nabla + D'$, where $D' = \sum_{M \in \mathfrak{M}} y_{i,\delta'\theta} \frac{\partial}{\partial y_{i\theta}}$.

$$[\delta, \delta'] \big|_R = 0.$$

$$[\delta, \delta'] (y_{i\theta}) = D(y_{i,\delta'\theta}) - D' (y_{i,\delta\theta}) = y_{i,\delta'\delta\theta} - y_{i,\delta\delta'\theta} = 0. \quad [\delta, \delta'] = 0.$$



Example: The Heat equation

$$\Delta = \{\partial_x, \partial_t\}$$

$$H = \partial_x^2 y - \partial_t y.$$

$$\text{card } \Delta = 2$$

Definition

Let $\mathcal{P} = \mathcal{R}\{y\}$ be the differential polynomial algebra. Let $F \in \mathcal{P}$. If $F \in \mathcal{R}$, we say the *order of F* is -1 . If $F \notin \mathcal{R}$, then the *order of F* is the highest order derivative θy_j dividing a monomial of F .

The order of H is 2.

Definition

Let \mathcal{R} be a Δ -ring. A family $z = (z_1, \dots, z_n)$ of a Δ - \mathcal{R} -algebra is *Δ -algebraically dependent over \mathcal{R}* if the family Θz is algebraically dependent over \mathcal{R} .

The single element z is called *Δ -algebraic over \mathcal{R}* if the family whose only element is z is Δ -algebraically dependent over \mathcal{F} .

Let $\Delta = \{\partial_x, \partial_t\}$. The incomplete gamma function

$$\gamma = \int_0^x s^{t-1} e^{-s} ds$$

is ∂_t -algebraically independent (∂_t -transcendentally transcendental) over both $\mathcal{F} = \mathbb{C}(x, t)$ and $\mathcal{G} = \mathbb{C}(x, t, x^{t-1}e^{-x}, \log x)$.

γ is ∂_x -algebraic over \mathcal{F} . It is a solution of the parametric linear homogeneous differential equation

$$\partial_x^2 y - \frac{t-1-x}{x} \partial_x y = 0,$$

Defining differential equations of the incomplete gamma function:

$$\begin{aligned}\partial_x^2 y - \frac{t-1-x}{x} \partial_x y &= 0, \\ \partial_x y \partial_t^2 \partial_x y - (\partial_t \partial_x y)^2 &= 0.\end{aligned}$$

Note that the family $(x^{t-1}e^{-x}, \log x)$ is algebraically independent over \mathcal{F} , but each of the elements is Δ -algebraically dependent over \mathcal{F} .

- 1 What do we mean by “all differential consequences of a system

$$P_i = 0 \quad (i \in I)$$

of differential polynomial equations?” (Drach, Picard)

- 2 What do we mean by the defining differential equations of γ ? (Drach, Picard)

Ritt's first answer to the first question: Consider the ideal in the differential polynomial ring generated by the P_i and all their derivatives.

Definition

An ideal α of a Δ -ring \mathcal{R} is a Δ -ideal if it is stable under Δ :

$$a \in \alpha \implies \delta a \in \alpha, \quad \delta \in \Delta.$$

Definition

Let \mathcal{R} be a Δ -ring.

- 1 $\mathcal{I}(\mathcal{R})$ is the set of all Δ -ideals of \mathcal{R} .
- 2 $\mathcal{R}(\mathcal{R})$ is the set of all radical Δ -ideals of \mathcal{R} .
- 3 $\mathcal{P}(\mathcal{R})$ is the set of all prime Δ -ideals of \mathcal{R} .

$$\mathcal{P}(\mathcal{R}) \subset \mathcal{R}(\mathcal{R}) \subset \mathcal{I}(\mathcal{R})$$

When we put a topology on $\mathcal{P}(\mathcal{R})$, we will call it $\text{diffspec}(\mathcal{R})$.

Example

$\mathcal{R} = \mathbb{Q}[x]$, $\delta = \frac{d}{dx}$. Let $\mathfrak{p} \in \mathfrak{P}(\mathcal{R})$, $\mathfrak{p} \neq (0)$.

$$\mathfrak{p} = (P), P \text{ irreducible.}$$

Suppose $\frac{dP}{dx} \neq 0$.

$$\deg \frac{dP}{dx} < \deg P, \text{ and } P \mid \frac{dP}{dx}.$$

Thus, $P \in \mathbb{Q} \rightsquigarrow \leftarrow$. Therefore, $\text{diffspec } \mathbb{Q}[x] = \text{diffspec } \mathbb{Q}(x)$.

Let \mathcal{R} be a Δ -ring.

Lemma

Let $(\mathfrak{a}_i)_{i \in I}$ be a family of elements of $\mathfrak{I}(\mathcal{R})$.

- 1 $\sum_{i \in I} \mathfrak{a}_i \in \mathfrak{I}(\mathcal{R})$.
- 2 $\bigcap_{i \in I} \mathfrak{a}_i \in \mathfrak{I}(\mathcal{R})$.
- 3 If $\forall i$ \mathfrak{a}_i is radical, then, $\bigcap_{i \in I} \mathfrak{a}_i$ is radical.

Lemma

Let \mathcal{R} be a Δ -ring, and let \mathfrak{a} and \mathfrak{b} be in $\mathfrak{I}(\mathcal{R})$.

- 1 $\mathfrak{a}\mathfrak{b} \in \mathfrak{I}(\mathcal{R})$.
- 2 $\mathfrak{a} \cap \mathfrak{b} \in \mathfrak{I}(\mathcal{R})$, and $\mathfrak{a}\mathfrak{b} \subset \mathfrak{a} \cap \mathfrak{b}$.

Definition

Let \mathcal{R} and \mathcal{S} be Δ -rings. A homomorphism

$$\varphi : \mathcal{R} \longrightarrow \mathcal{S}$$

is a Δ -homomorphism if

$$\varphi \circ \delta = \delta \circ \varphi, \quad \delta \in \Delta.$$

If \mathcal{R} and \mathcal{S} are $\Delta\text{-}\mathcal{R}_0$ -algebras, we call φ a $\Delta\text{-}\mathcal{R}_0$ -homomorphism if $\varphi|_{\mathcal{R}_0} = \text{id}$.

Definition

Let \mathcal{R} and \mathcal{S} be Δ -rings, and let $\varphi : \mathcal{R} \longrightarrow \mathcal{S}$ be a Δ -homomorphism.

- 1 ${}^i\varphi : \mathfrak{I}(\mathcal{S}) \longrightarrow \mathfrak{I}(\mathcal{R}),$
- 2 ${}^r\varphi : \mathfrak{R}(\mathcal{S}) \longrightarrow \mathfrak{R}(\mathcal{R}),$
- 3 ${}^p\varphi : \mathfrak{P}(\mathcal{S}) \longrightarrow \mathfrak{P}(\mathcal{R})$

are defined by the same formula $\mathfrak{b} \longmapsto \varphi^{-1}(\mathfrak{b})$.

Note that $\ker \varphi \in \mathfrak{I}(\mathcal{R})$. $\varphi(\mathcal{R})$ is a Δ -subring of \mathcal{S} .

Lemma

Let \mathcal{R} and \mathcal{S} be Δ -rings, and let $\varphi : \mathcal{R} \rightarrow \mathcal{S}$ be a surjective Δ -homomorphism.

- 1 $\ker \varphi \in \mathfrak{P}(\mathcal{R}) \iff \mathcal{S}$ is an integral domain.
- 2 $\ker \varphi \in \mathfrak{R}(\mathcal{R}) \iff \mathcal{S}$ is reduced (no nonzero nilpotent elements).
- 3 ${}^i\varphi$ maps $\mathfrak{I}(\mathcal{S})$ bijectively onto the set of Δ -ideals of \mathcal{R} containing $\ker \varphi$.
- 4 ${}^r\varphi$ maps $\mathfrak{R}(\mathcal{S})$ bijectively onto the set of radical Δ -ideals of \mathcal{R} containing $\ker \varphi$.
- 5 ${}^p\varphi$ maps $\mathfrak{P}(\mathcal{S})$ bijectively onto the set of prime Δ -ideals of \mathcal{R} containing $\ker \varphi$.

In the last three statements, the maps are inclusion preserving and their inverses send \mathfrak{a} to $\varphi(\mathfrak{a})$.

Lemma

Let \mathfrak{a} be Δ -ideal in a Δ -ring \mathcal{R} . Then \mathcal{R}/\mathfrak{a} has a unique structure of Δ -ring such that the quotient homomorphism $\pi : \mathcal{R} \rightarrow \mathcal{S}$ is a Δ -homomorphism.

Proof.

For $\delta \in \Delta$ and $x \in \mathcal{R}$, set $\bar{x} = x + \mathfrak{a}$, and define $\delta\bar{x} = \overline{\delta x}$. Let $y \in \mathcal{R}$. Suppose $\bar{x} = \bar{y}$.

$$\begin{aligned}x - y &\in \mathfrak{a}. \\ \delta(x - y) &= \delta x - \delta y \in \mathfrak{a}. \\ \delta\bar{x} &= \delta\bar{y}.\end{aligned}$$

So, the action of Δ on \mathcal{R}/\mathfrak{a} is well-defined. The sum and product rules follow easily. □

Corollary

Let α be Δ -ideal in a Δ -ring \mathcal{R} . Let π be the quotient homomorphism.

- 1 π maps $\mathfrak{I}(\mathcal{R}/\alpha)$ bijectively onto the set of Δ -ideals of \mathcal{R} containing α .
- 2 π maps $\mathfrak{R}(\mathcal{R}/\alpha)$ bijectively onto the set of radical Δ -ideals of \mathcal{R} containing α .
- 3 π maps $\mathfrak{P}(\mathcal{R}/\alpha)$ bijectively onto the set of prime Δ -ideals of \mathcal{R} containing α .

Definition

Let \mathcal{R} be a Δ -ring and α be a Δ -ideal of \mathcal{R} . The Δ -ideal α is *generated by a subset* S if the ideal α is generated by ΘS .

We denote it by $[S]$. Call S a (Δ -ideal) basis of α . $[S]$ is the smallest Δ -ideal containing S .

Question (Drach, Picard): Is every system of differential polynomial equations equivalent to a finite system?

If \mathcal{R} is a ring finitely generated over a field, every ideal of \mathcal{R} is finitely generated. So, the answer is yes for polynomial equations.

Example

Let $\mathcal{R} = \mathcal{F}\{y\}$, \mathcal{F} a Δ -field, $\Delta = \{\delta\}$, y a Δ -indeterminate over \mathcal{F} .
Write $y', y'', \dots, y^{(i)}, \dots$

$$\mathfrak{i} = [yy', y'y'', \dots, y^{(i)}y^{(i+1)}, \dots]$$

has no finite Δ -ideal basis (Ritt, 1930 Also, see Kovacic-Churchill, Notes KSDA).

Radicals redux

Let \mathcal{R} be a Δ -ring. Let \mathfrak{a} be a Δ -ideal of \mathcal{R} . The intersection of the family of radical Δ -ideals of \mathcal{R} containing \mathfrak{a} is a radical Δ -ideal.

So, there is a *smallest radical Δ -ideal of \mathcal{R} containing \mathfrak{a}* .

The radical $\sqrt{\mathfrak{a}}$ is the set of $a \in \mathcal{R}$ such that there is a positive integer n with $a^n \in \mathfrak{a}$. It is an ideal of \mathcal{R} , and is the smallest radical ideal of \mathcal{R} containing \mathfrak{a} . Is it a Δ -ideal? Conjecture: Yes.

Example

Let $\mathcal{R} = \mathbb{Z}[x]$, $\delta = \frac{d}{dx}$.

Let $\mathfrak{a} = (2, x^2)$. \mathfrak{a} is a δ -ideal of \mathcal{R} . Let $\mathcal{S} = \mathcal{R}/\mathfrak{a}$. $\bar{x} \in \sqrt{[0]}$. $\delta\bar{x} = 1 \notin \sqrt{[0]}$.

Is this a counterexample to the conjecture? No. Our Δ -rings are Ritt algebras.

Theorem

Let \mathcal{R} be a Δ -ring (Ritt algebra), and let α be a Δ -ideal of \mathcal{R} . Then, the radical of α is a Δ -ideal of \mathcal{R} .

If $\alpha = [S]$, call $\tau = \sqrt{\alpha}$ the *radical Δ -ideal generated by S* . S is also called a (*radical Δ -ideal*) *basis* for the radical Δ -ideal τ .

Proof.

Let $a \in \sqrt{\alpha}$. Let $n \in \mathbb{Z}_{>0}$ be such that $a^n \in \alpha$. Claim: For any $\delta \in \Delta$, $k = 0, \dots, n$,

$$a^{n-k} (\delta a)^{2k} \in \alpha.$$

By hypothesis, the case $k = 0$ is true. Let $0 \leq k \leq n - 1$. Assume true for k . Differentiate.

$$(n - k) a^{n-k-1} (\delta a)^{2k+1} + 2ka^{n-k} (\delta a)^{2k-1} (\delta^2 a) \in \alpha$$

by the induction hypothesis.

$$\delta a[(n - k) a^{n-k-1} (\delta a)^{2k+1} + 2ka^{n-k} (\delta a)^{2k-1} (\delta^2 a)] \in \alpha$$

$$a^{n-k-1} (\delta a)^{2k+2} \in \alpha.$$

by the induction hypothesis, and, since \mathcal{R} is a Ritt algebra. So, the claim is true for $k + 1$. Set $k = n$. □

The Ritt basis theorem

Theorem

Let \mathcal{F} be a Δ -field, and $\mathcal{R} = \mathcal{F}\{z_1, \dots, z_n\}$ be a finitely Δ -generated Δ - \mathcal{F} -algebra. Then, every radical Δ -ideal has a finite (radical Δ -ideal) basis.

Set $\mathcal{R} = \mathcal{F}\{y_1, \dots, y_n\}$, y_1, \dots, y_n Δ -indeterminates. Let Σ be any subset of \mathcal{R} . The radical Δ -ideal $\tau = \sqrt{[\Sigma]}$ has a finite basis. There is a finite subset F_1, \dots, F_r of τ such that $\tau = \sqrt{[F_1, \dots, F_r]}$. The radical Δ -ideal $\tau = \sqrt{[\Sigma]}$ is Ritt's final interpretation of "all differential consequences of the system

$$F = 0, \quad F \in \Sigma."$$

The basis theorem is his answer to Drach-Picard: Is every system of differential polynomial equations equivalent to a finite system?

The solution space of the system defined by Σ is also defined by

$$F_1 = 0, \dots, F_r = 0.$$

Zeros of differential polynomials and ideals

Let \mathcal{R} be a Δ -ring and $y = (y_1, \dots, y_n)$ be a family of Δ -indeterminates over \mathcal{R} . Let $\mathcal{S} = \mathcal{R}\{y\}$.

$$\mathcal{S}_r = \mathcal{R}[\theta y]_{\theta \in \Theta(r)}.$$

Let $z = (z_1, \dots, z_n) \in \mathcal{R}^n$. Then, $z \leftrightarrow (z, \delta_1 z, \dots, \delta_m z, \dots, \theta z, \dots)$. On each polynomial ring \mathcal{S}_r we have the substitution homomorphism

$$\mathcal{S}_r \longrightarrow \mathcal{R}, \quad (\theta y) \longmapsto (\theta z), \theta \in \Theta.$$

This defines a Δ - \mathcal{R} -homomorphism σ_z from \mathcal{S} into \mathcal{R} , called the Δ -substitution homomorphism. For $P \in \mathcal{S}$, write $P(z)$ for $\sigma_z(P)$, and call it the *value* of P at z . $\ker \sigma_z$ is a Δ -ideal of \mathcal{S} , called the *defining Δ -ideal* of z .

Example

Let $\Delta = \{\partial_x, \partial_t\}$, \mathcal{F} the Δ -field of functions meromorphic in $\mathbb{D}_x \times \mathbb{D}_t$, where \mathbb{D}_x is the right half plane of \mathbb{C} , $\mathbb{D}_t = \mathbb{C} \setminus \mathbb{Z}_{\leq 0}$. Let $\gamma = \int_0^x s^{t-1} e^{-s} ds \in \mathcal{F}$. The defining Δ -ideal of γ in $\mathcal{F}\{y\}$ is the prime Δ -ideal

$$\mathfrak{p} = \left[\partial_x^2 y - \frac{t-1-x}{x} \partial_x y, \partial_x y \partial_t^2 \partial_x y - (\partial_t \partial_x y)^2 \right].$$

Definition

Let \mathcal{R} be a Δ -ring, $y = (y_1, \dots, y_n)$ a family of Δ -indeterminates over \mathcal{R} , $\mathcal{S} = \mathcal{R}\{y\}$. Let Σ be a subset of \mathcal{S} . The *zero set* of Σ is the set

$$Z = \{z \in \mathcal{R}^n : P(z) = 0, \quad P \in \Sigma\}.$$

Example

Set

$$\Sigma = \left\{ \partial_x^2 y - \frac{t-1-x}{x} \partial_x y, \partial_x y \partial_t^2 \partial_x y - (\partial_t \partial_x y)^2 \right\},$$

\mathcal{F} as above. Determine $Z \subset \mathcal{F}$. The zero set of $L = \partial_x^2 y - \frac{t-1-x}{x} \partial_x y$ is

$$\begin{aligned} V &= \{c_0(t) + c_1(t)\gamma\}, \\ \gamma &= \int_0^x s^{t-1} e^{-s} ds \in \mathcal{F} \end{aligned}$$

Let

$$z = c_0(t) + c_1(t)\gamma.$$

Then, $\partial_x z = 0$ if and only if $c_1(t) = 0$. So, suppose $c_1(t) \neq 0$. Then, z is a zero of the second polynomial

$$\partial_x y \partial_t^2 \partial_x y - (\partial_t \partial_x y)^2$$

if and only if

$$\partial_t (\ell \partial_t \partial_x z) = 0, \quad \ell \partial_t \partial_x z = \frac{\partial_t \partial_x z}{\partial_x z}.$$

$$\partial_x z = c_1(t) \partial_x \gamma = c_1(t) x^{t-1} e^{-x}.$$

$$\begin{aligned} \ell \partial_t \partial_x z &= \ell \partial_t c_1(t) + \ell \partial_t (x^{t-1} e^{-x}) \\ &= \ell \partial_t c_1(t) + \log x \end{aligned}$$

$$\partial_t (\ell \partial_t \partial_x z) = \partial_t \ell \partial_t c_1(t).$$

$$Z = \mathcal{F}^{\partial_x} \cdot 1 \cup (\mathcal{F}^{\partial_x} \cdot 1 + G \cdot \gamma),$$

where G is the subgroup of the multiplicative group of \mathcal{F}^{∂_x} satisfying the differential equation

$$\partial_t \left(\frac{\partial_t y}{y} \right) = 0.$$

$$G\gamma = k_1 e^{k_2 t} \int_0^x s^{t-1} e^{-s} ds, \quad k_1, k_2 \in \mathbb{C}.$$

G is a *differential algebraic group*.